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Abstract

For a power assisted steering system for vehicles, in particular passenger cars, there is provision to form 10 hydraulic circuit with servopump and with three-way flow regulator valve which is located at the junction between the pump and the servoactuator and has a measuring throttle, located in the inflow to the servoactuator, as a fixed throttle and an outflow 15 throttle which is located in a bypass of the latter and which determines a variable throttle cross section by means of a piston which is charged alternately as a pressure compensator, the piston, which is charged via 20 active actuator element, changes the outflow throttle cross section as a function of the current applied in order to change the volume flow which passes via the measuring throttle.